



KVASER USBcan Pro 4xHS

EAN: 73-30130-01261-5

The Kvaser USBcan Pro 4xHS is an advanced, portable multi-channel CAN to USB real time interface that handles transmission and reception of standard and extended CAN messages on the CAN bus with a high time stamp precision. Features include t programming and MagiSyncTM, which makes it possible to synchronise time stamps across multiple Kvaser MagiSyncTM-enabled devices without requiring extra wires.

Warranty

2-year warranty. See our General Conditions and Policies for details.

Support

Free support for all products by contacting support@kvaser.com.



Major Features

- Multi-channel USB CAN interface with Kvaser t programmability.
- 20 000 msg/s per channel, each timestamped with a resolution of 1 μ s.
- Kvaser MagiSync[™] automatic time synchronization.
- Supports CAN FD, up to 8 Mbit/s (with correct physical layer implementation).
- Supports both 11-bit (CAN 2.0A) and 29-bit (CAN 2.0B active) identifiers.
- Supports silent mode for analysis tools
 listen to the bus without interfering.
- High-speed CAN connection (compliant with ISO 11898-2), up to 1 Mbit/s.
- Fully compatible with J1939, CANopen, NMEA 2000® and DeviceNet.
- Simultaneous operation of multiple devices.
- · Power is taken from the USB bus.
- Includes a 4-channel breakout cable.

Technical Data

| CAN Bit Rate | 40 kbit/s to 1 Mbit/s |
|--------------------------------|-----------------------|
| CAN FD | Yes |
| CAN FD Bit Rate | Up to 8 Mbit/s |
| CAN Channels | 4 |
| CAN Transceivers | MCP2561FD |
| Certifications | CE, RoHS |
| Connector | DSUB 9 |
| Current Consumption | Max 500 mA |
| Dimensions | 50 x 170 x 20 mm |
| Galvanic Isolation | Yes |
| IP Rating Housing | IP40 |
| Operating Temperature Range | -40 °C to +85 °C |
| Silent Mode | Yes |
| Timestamp Resolution | 1 μs |
| Weight | 150 g |
| Operating Systems | Windows, Linux |
| | |

Software

Documentation, Kvaser CANlib SDK and drivers can be downloaded for free at www.kvaser.com/downloads.

Kvaser CANlib SDK is a free resource that includes everything you need to develop software for the Kvaser CAN interfaces. Includes full documentation and many program samples, written in C, C++, C#, Delphi, Visual Basic, Python and t programming language.

Kvaser CAN hardware is built around the same common software API. Applications developed using one device type will run without modification on other device types





